Technical data sheet

TFB120-SR

Basic Fail-Safe modulating actuator for controlling dampers in typical commercial HVAC applications.

- Torque motor 22 in-lb [2.5 Nm]
- Nominal voltage AC 100...240 V
- Control Modulating
- Position feedback 2...10 V







Technical data

 	 data

Nominal voltage	AC 100240 V	
Nominal voltage frequency	50/60 Hz	
Nominal voltage range	AC 85265 V	
Power consumption in operation	2.5 W	
Power consumption in rest position	2 W	
Transformer sizing	5.5 VA	
Electrical Connection	(2) 18 GA appliance cables, 1 m, with 1/2" NPT conduit connectors	
Overload Protection	electronic throughout 095° rotation	
Electrical Protection	actuators are double insulated	
Torque motor	22 in-lb [2.5 Nm]	

Functional data

Torque motor	22 in-lb [2.5 Nm]		
Operating range Y	210 V		
Operating range Y note	420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)		
Input impedance	100 k Ω for 210 V (0.1 mA), 500 Ω for 420 mA		
Position feedback U	210 V		
Position feedback U note	Max. 0.5 mA		
Direction of motion motor	selectable with switch 0/1		
Direction of motion fail-safe	reversible with cw/ccw mounting		
Angle of rotation	Max. 95°		
Angle of rotation note	adjustable with mechanical stop		
Running Time (Motor)	95 s /		
Running time motor note	constant, independent of load		
Running time fail-safe	<25 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]		
Noise level, motor	35 dB(A)		
Noise level, fail-safe	62 dB(A)		
Position indication	Mechanical		

Safety data

Degree of protection IEC/EN	IP42
Degree of protection NEMA/UL	NEMA 2
Enclosure	UL Enclosure Type 2
Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02 CE acc. to 2014/30/EU and 2014/35/EU
Quality Standard	ISO 9001
UL 2043 Compliant	Suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the IMC
Ambient humidity	Max. 95% RH, non-condensing
Ambient temperature	-22122°F [-3050°C]
Storage temperature	-40176°F [-4080°C]



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Safety data	Servicing	maintenance-free	
Weight	Weight	1.8 lb [0.83 kg]	
Materials	Housing material	UL94-5VA	

Footnotes †Rated Impulse Voltage 4kV, Type of action 1.AA, Control Pollution Degree 3.

Product features

Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft from 1/4" up to 1/2" in diameter by means of its universal clamp, 1/2" shaft centered at delivery. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a 2 to 10 VDC, or with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication.

Operation

The TF series actuators provide true spring return operation for reliable fail-safe application and positive close-off on air tight dampers. The spring return system provides consistent torque to the damper with, and without, power applied to the actuator. The TF series provides 95° of rotation and is provided with a graduated position indicator showing 0 to 95°. The TF uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. Power consumption is reduced in holding mode. The actuator is double insulated so an electrical ground connection is not necessary.

Safety Note: Screw a conduit fitting into the actuator's bushing. Jacket the actuator's input and output wiring with suitable flexible conduit. Properly terminate the conduit in a suitable junction box.

Typical specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a shaft up to a 1/2" diameter and center on a 1/2" shaft. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuator must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. If required, one SPDT auxiliary switch shall be provided having the capability of being adjustable. Actuators with auxiliary switch must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed, have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



Accessories

Electrical accessories	Description	Туре
	DC Voltage Input Rescaling Module	IRM-100
	Auxiliary switch, mercury-free	P475
	Auxiliary switch, mercury-free	P475-1
	Signal simulator, Power supply AC 120 V	PS-100
	Convert Pulse Width Modulated Signal to a 210 V Signal for Belimo	PTA-250
	Proportional Actuators	
	Positioner for wall mounting	SGA24
	Positioner for front-panel mounting	SGF24
	Cable conduit connector 1/2"	TF-CC US
	Resistor, 500 Ω , 1/4" wire resistor with 6" pigtail wires	ZG-R01
	Resistor kit, 50% voltage divider	ZG-R02
Mechanical accessories	Description	Туре
	Shaft extension 170 mm ø10 mm for damper shaft ø616 mm	AV6-20
	Position indicator	IND-TF
	for TFB(X)	
	Shaft clamp	K8 US
	for TFB(X)	
	Ball joint suitable for damper crank arm KH8 / KH10	KG10A
	Ball joint suitable for damper crank arm KH8	KG6
	Ball joint suitable for damper crank arm KH8	KG8
	Damper crank arm Slot width 8.2 mm, for ø1.05"	KH12
	Damper crank arm Slot width 6.2 mm, clamping range ø1018 mm	KH6
	Damper crank arm Slot width 8.2 mm, clamping range ø1018 mm	KH8
	TFB(X) crankarm with 5/16" slot.	KH-TF US
	TFB(X) crankarm with 1/4" slot.	KH-TF-1 US
	Screw fastening kit	SB-TF
	Push rod for KG10A ball joint 36" L, 3/8" diameter	SH10
	Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
	Anti-rotation bracket TF/NKQ/AM/NM/LM.	TF-P
	Wrench 0.32 in and 0.39 in [8 mm and 10 mm]	TOOL-06
	Angle of rotation limiter, with end stop	ZDB-TF
	Mounting bracket	ZG-113
	for TFB(X)	
	Damper clip for damper blade, 3.5" width.	ZG-DC1
	Damper clip for damper blade, 6" width.	ZG-DC2
	Shaft extension for 3/8" diameter shafts (4" L).	ZG-LMSA-1
	Shaft extension for 1/2" diameter shafts (5" L).	ZG-LMSA-1/2-5
	TFB(X) crankarm adaptor kit (includes ZG-113).	ZG-TF112
	TFB(X) crankarm adaptor kit (T bracket included).	ZG-TF2
	Mounting kit	ZG-TF3
	for TFB(X)	
	Weather shield 13x8x6" [330x203x152 mm] (LxWxH)	ZS-100
	Baseplate, for ZS-100	ZS-101
	Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150

Electrical installation



/ Warning! Live electrical components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Meets cULus requirements without the need of an electrical ground connection.

A Actuators with appliance cables are numbered. The Provide overload protection and disconnect as required.

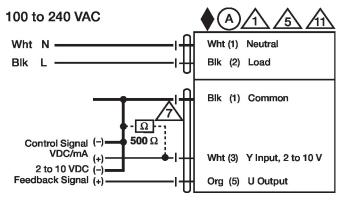


6 Only connect common to negative (-) leg of control circuits.

 Λ A 500 Ω resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.



Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.



2...10 V / 4...20 mA Control

Dimensions

